

1. K-core

Let $G=(V,E)$ be a simple graph.

The ^A (maximum) K-core is the maximum sized subgraph where all vertices have induced degree at least K. Equivalently, S^* is a K-core if

$$\bullet \min_{v \in S^*} d_v(S^*) \geq K$$

⑥ If $T \subseteq V$ satisfies $\min_{v \in T} d_v(T) \geq K$
then $T \subseteq \underline{S^*}$

* differs slightly from some definitions of K-core — we'll reconcile differences later.

Claim: $\underline{S^*}$ is unique.

Assume not. Then assume $\tilde{S}$ is also a maximum K-core with $\tilde{S} \neq S^*$.

$Q = \tilde{S} \cup S^*$ is larger than $\tilde{S}$ and S^* and contains both of them and $\min_{v \in Q} d_v(Q) \geq K$

and this contradicts the second point in the definition, hence S^* must be unique.

Algorithm (Peeling)

Consider an algorithm that repeatedly removes the min degree node.

Alg

$S_0 = V$

for $i = 1, 2, \dots, n$

$w = \operatorname{argmin} d_v(S_{i-1})$

 if $d_w(S_{i-1}) \geq k$

 return S_{i-1}

 else

$S_i = S_{i-1} \setminus \{w\}$

 end

end

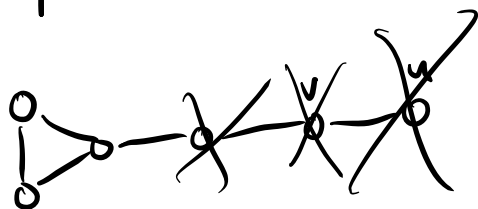
Let T be the set returned

by this algorithm.

Claim: $T = S^*$

Observe that if a node is removed, it cannot be in the K -core, because it was removed at a point when it had induced degree $< K$.

Example: $K=2$



This means if $v \notin T$ then $v \notin S^*$

Next observe if T is the set output by the algorithm, then for $j \in T$, $d_j(T) \geq K$ so T certainly is contained in the K -core S^* by the second point of the definition of K -core. In other words

if $v \in T$ then $v \in S^*$

So $T = S^*$.



Running time $O(E)$

Nested Structure

Above, we stopped as soon as we found the K -core, but if we keep going, we find all the K -cores.

Def: The "coreness" number of a node $v \in V$ is the value c such that v belongs to the c -core but not the $(c+1)$ -core.

Alg: All cores

$$S_0 = V$$

$$\text{currentcore} = 0$$

$$n = |V|$$

coreness = zeros(n) // array of zeros

for $i = 1, 2, \dots, n$

$$w = \operatorname{argmin} d_v(S_{i-1})$$

$$d_w = d_w(S_{i-1})$$

if $d_w > \text{currentcore}$

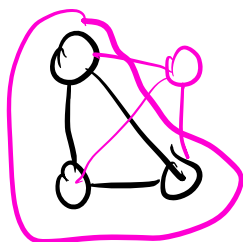
$$\quad \text{currentcore} = d_w$$

end

$$\text{coreness}[w] = \text{currentcore} \quad \leftarrow$$

$$S_i = S_{i-1} \setminus \{w\}$$

end



$$K = 3$$

Proposition: For any $K \in \mathbb{N}$ the K -core is given by one of

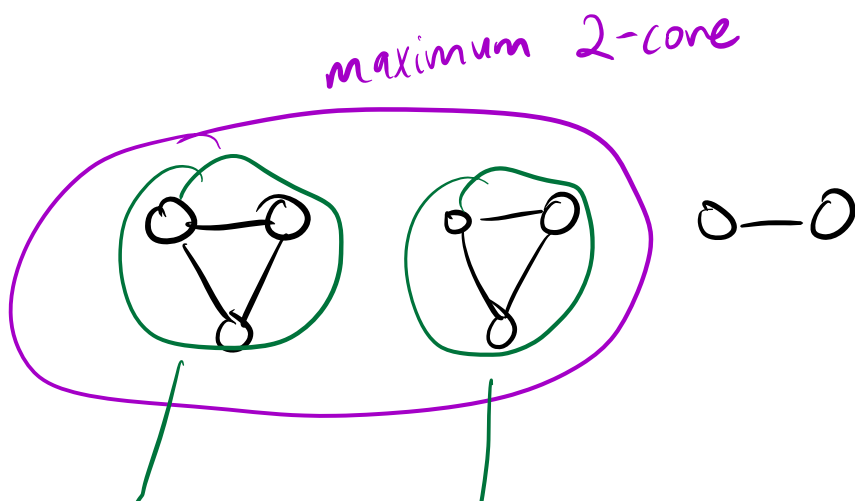
$$S_0 \supseteq S_1 \supseteq S_2 \supseteq \dots \supseteq S_n = \emptyset$$

so the K -cores define a nested structure of subgraphs.

Reconciling Definitions

Some definitions require a K -core to be a maximal connected subgraph where induced degree is $\geq K$ for all nodes.

E.g.



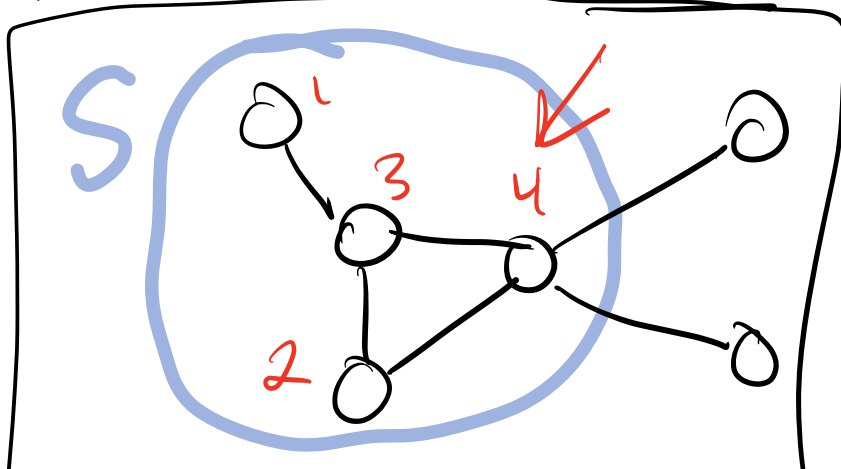
$\downarrow$ $\downarrow$
 a 2-core a 2-core

We can find these maximal connected K -cores by finding connected components of our maximum K -core.

2. Densest subgraph Problem

Goal: find $S^* = \operatorname{argmax}_{S \subseteq V} \frac{|E(S^*)|}{|S^*|}$

Recall that $\operatorname{val}(S) - \operatorname{cut}(S) = \underline{\underline{2|E(S)|}}$



$$\text{val}(S) = 10$$

$$|E(S)| = \frac{\text{val}(S) - \text{cut}(S)}{2}$$

So we want to equivalently find

$$\boxed{\text{argmax} = \frac{|E(S)|}{|S|}} = \text{argmax} \frac{\text{val}(S) - \text{cut}(S)}{2|S|}$$

$$= \text{argmax} \frac{\text{val}(S) - \text{cut}(S)}{|S|}$$

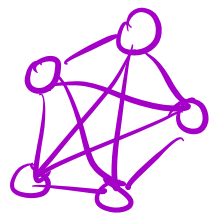
$$= \boxed{\text{argmin} \frac{|S|}{\text{val}(S) - \text{cut}(S)}}$$

$$\frac{\frac{n(n-1)}{2}}{n}$$

Side note: $\gamma(S) = \frac{|E(S)|}{|S|}$



Then $\frac{1}{2} \leq \gamma(S^*) \leq \frac{n-1}{2}$



n nodes

(assuming here a connected simple graph with $|V| \geq 2$)

So $\frac{2}{n-1} \leq \frac{2|S^*|}{\text{vol}(S^*) - \text{cut}(S^*)} \leq 2$

$\Rightarrow \frac{1}{n-1} \leq \frac{|S^*|}{\text{vol}(S^*) - \text{cut}(S^*)} \leq 1$

$f(S) = \frac{|S|}{\text{vol}(S) - \text{cut}(S)}$

Decision Version

For $\alpha \in [\frac{1}{n-1}, 1]$, is there
some set $S \subseteq V$ such that
 $f(S) < \alpha$?

We can answer this by solving:

$$\min_{S \subseteq V} \underline{g(S)} = \underline{|S|} - \underline{\alpha \text{val}(S)} + \underline{\alpha \text{cut}(S)}$$

Fact: $g(S) < 0$, then $f(S) < \alpha$

$$|S| - \alpha \text{val}(S) + \alpha \text{cut}(S) < 0$$

$$|S| < \alpha \text{val}(S) - \alpha \text{cut}(S)$$

$$f(S) = \frac{|S|}{\text{val}(S) - \text{cut}(S)} < \alpha$$

Note that adding $\alpha \text{vol}(V)$ does not change the optimization:

$$\operatorname{argmin}_{S \subseteq V} g(S) = \operatorname{argmin}_{S \subseteq V} g(S) + \alpha \text{vol}(V)$$

$$= \operatorname{argmin}_{S \subseteq V} |S| - \underbrace{\alpha \text{vol}(S) + \alpha \text{vol}(V) + \alpha \text{cut}(S)}$$

$$(1) = \operatorname{argmin}_{S \subseteq V} |S| + \alpha \text{vol}(\bar{S}) + \alpha \text{cut}(S)$$

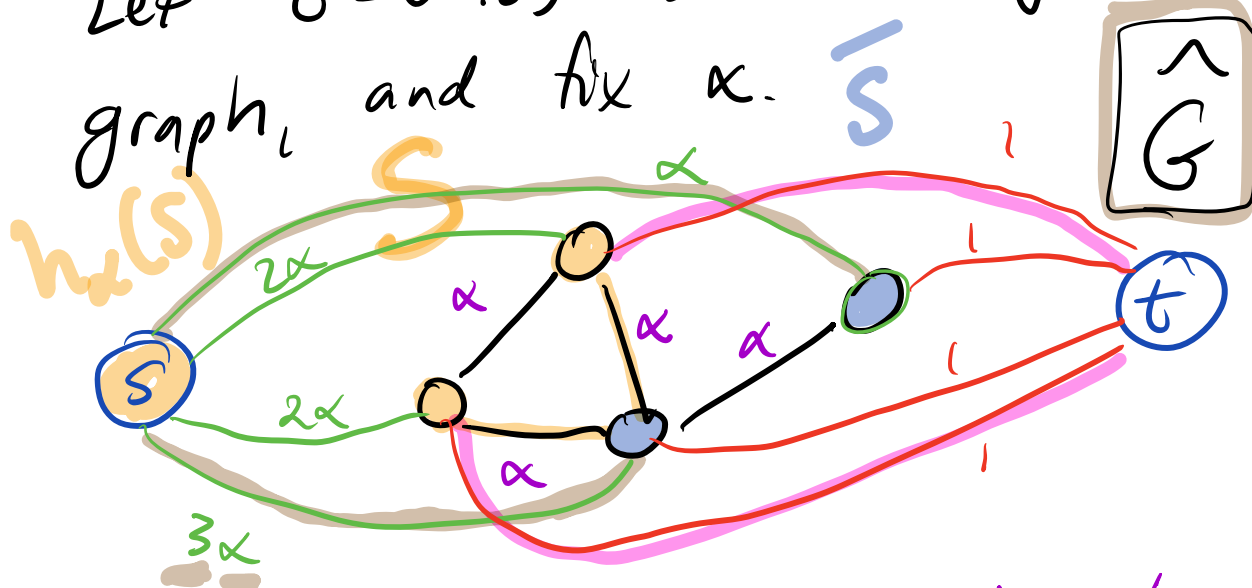
Proposition: Objective (1) can be solved via a single minimum s - t cut problem in an augmented graph.

$$h_\alpha(S) = |S| + \alpha \text{vol}(\bar{S}) + \alpha \text{cut}(S)$$

Note: $h_\alpha(S) < \alpha \text{vol}(V) \Leftrightarrow f(S) < \alpha$

The s - t cut construction

Let $G=(V,E)$ be the original graph, and fix α .



Step 1: weight all original edges by α

Step 2: add s and t node

Step 3: For $v \in V$, add edge (s,v) of weight αd_v

Step 4: add edge (v,t) of weight 1 .

$$h_\alpha(s) = |S| + \alpha \text{val}(\bar{S}) + \alpha \text{cut}(S)$$

Proposition: For every $S \subseteq V$
the value of the s - t cut
 $S \cup \{s\}$ in $\hat{G}$ is exactly
 $h_\alpha(S)$.

Full Procedure for minimizing $f(S)$

- If $\min h_\alpha(S) < 0$, then $\exists$ a set $\hat{S}$ such that $f(\hat{S}) < \alpha$.

We can then choose a new $\hat{\alpha} = f(\hat{S})$
and minimize $h_{\hat{\alpha}}(S)$.

- If $\min h_\alpha(S) = \alpha \text{vol}(V)$, then
there is no S with $f(S) < \alpha$.

Algorithm

$$\alpha \leftarrow 1$$

$$S_\alpha = \operatorname{argmin} h_\alpha(S)$$

$$\alpha_{\text{new}} = \underline{f(S_\alpha)} = \frac{|S_\alpha|}{\operatorname{vol}(S_\alpha) - \operatorname{cut}(S_\alpha)}$$

while $\alpha_{\text{new}} < \alpha$

$$\hat{S} = S_\alpha$$

$$\alpha = \alpha_{\text{new}}$$

$$S_\alpha = \operatorname{argmin} h_\alpha(S)$$

$$\alpha_{\text{new}} = f(S_\alpha)$$

end

return $\hat{S}, \gamma(\hat{S}) =$

$$\frac{|E(\hat{S})|^\leftarrow}{|\hat{S}|}$$

At most 2^n possible α values

$$\log 2^n \rightarrow O(n)$$

2. Peeling Algorithms

Recall that an equivalent problem is maximizing the average induced degree

$$\max_{S \subseteq V} \delta(S) = \frac{\sum_{v \in S} d_v(S)}{|S|} = \max_{S \subseteq V} \frac{2|E(S)|}{|S|}$$

A greedy peeling algorithm gives a 2-approximation.

Alg.

$$S_0 = V$$

for $i = 1, 2, \dots, n-1$

$$w_i = \operatorname{argmin}_{v \in S_{i-1}} d_v(S_{i-1})$$

$$S_i = S_{i-1} \setminus \{w_i\}$$

end

return S_i with max average degree

Proposition: There is some $\underline{i}$ such that

$$\delta(S_i) \geq \frac{1}{2} \max_{S \subseteq V} \delta(S)$$

Proof: Let $d^* = \max \delta(S)$

$$= \delta(S^*) = \frac{\sum_{v \in S^*} d_v(S^*)}{|S^*|}$$

This means $\sum_{v \in S^*} d_v(S^*) - d^* |S^*| = 0$

Since S^* is optimal, removing a single vertex would make the average degree worse, so for every $j \in S^*$

$$\frac{\left[\sum_{v \in S^*} d_v(S^*) \right] - 2d_j(S^*)}{|S^*| - 1} \leq d^*$$

$$\Rightarrow \sum_{v \in S^*} d_v(S^*) - 2d_j(S^*) \leq d^* |S^*| - d^*$$

$$\Rightarrow d_j(S^*) \geq \frac{d^*}{2}$$

The greedy algorithm removes one node at a time, inducing an order $w_1, w_2, \dots, w_{n-1}$

Let j be the first node in S^* that I remove during this process.
Consider S_{j-1} . Note that $S_{j-1} \supseteq S^*$

hence $d_v(S_{j-1}) \geq d_v(S^*) \quad \forall v \in S^*$

We know $d_j(S_{j-1})$ is the smallest induced degree in S_{j-1} , so it is smaller than the average degree in S_{j-1} :

$$\begin{aligned} \underline{\underline{\frac{d^*}{2}}} &\leq d_j(S^*) \leq d_j(S_{j-1}) \\ &\leq \frac{\sum_{i \in S_{j-1}} d_i(S_{j-1})}{|S_{j-1}|} = \underline{\underline{\delta(S_{j-1})}} \end{aligned}$$

QED.

3. LP for densest subgraph problem

$$\max \sum_{(i,j) \in E} x_{ij}$$

$$f(S) = \frac{|E(S)|}{|S|}$$

$$\forall ij \in E \quad x_{ij} \leq y_i$$

$$x_{ij} = \min \{y_i, y_j\}$$

$$x_{ij} \leq y_j$$

$$\sum_{i=1}^n y_i \leq 1$$

$$x_{ij}, y_i \geq 0$$

Prop 1: Let OPT be the optimal LP solution. For every $S \subseteq V$ $f(S) \leq \text{OPT}$.

Proof: Let $x = \frac{1}{|S|}$, and set

$$\hat{y}_i = x \quad \forall i \in S$$

$$\hat{x}_{ij} = x \quad \forall ij \in E(S)$$

Set all other variables to zero. Then

$$\sum_{ij \in E} x_{ij} = \sum_{ij \in E(S)} \hat{x}_{ij} + 0 = \sum_{ij \in E(S)} \frac{1}{|S|} = \boxed{\frac{|E(S)|}{|S|}}$$

This is a feasible LP solution:

$$ij \in E(S) \quad \hat{x}_{ij} = x = y_i = y_j$$

$$ij \in \partial S \quad \hat{x}_{ij} = 0 < x$$

$$\sum_{i=1}^n y_i = \sum_{i \in S} \frac{1}{|S|} = 1$$

Prop: We can find a set S
such that $f(S) \geq \text{OPT}$.

Proof: Let $\{\underline{x}, \underline{y}\}$ be the
optimal LP solution.

Assume WLOG $x_{ij} = \min\{y_i, y_j\}$

For a parameter $r \geq 0$ define

$$S_r = \{i \in V : \underline{y}_i \geq r\}$$

$$E_r = \{(i, j) \in E : \underline{x}_{ij} \geq r\}$$

Observe $\underline{E}_r = \underline{E}(S_r)$

If $\underline{(i, j)} \in E_r$, then $\left. \begin{array}{l} \boxed{y_i} \geq x_{ij} \geq r \\ \boxed{y_j} \geq x_{ij} \geq r \end{array} \right\} \begin{array}{l} i \in S_r \\ j \in S_r \end{array}$

$$\Rightarrow ij \in \boxed{E(S_r)}$$

If $ij \in E(S_r)$ then $i \in S_r, j \in S_r$

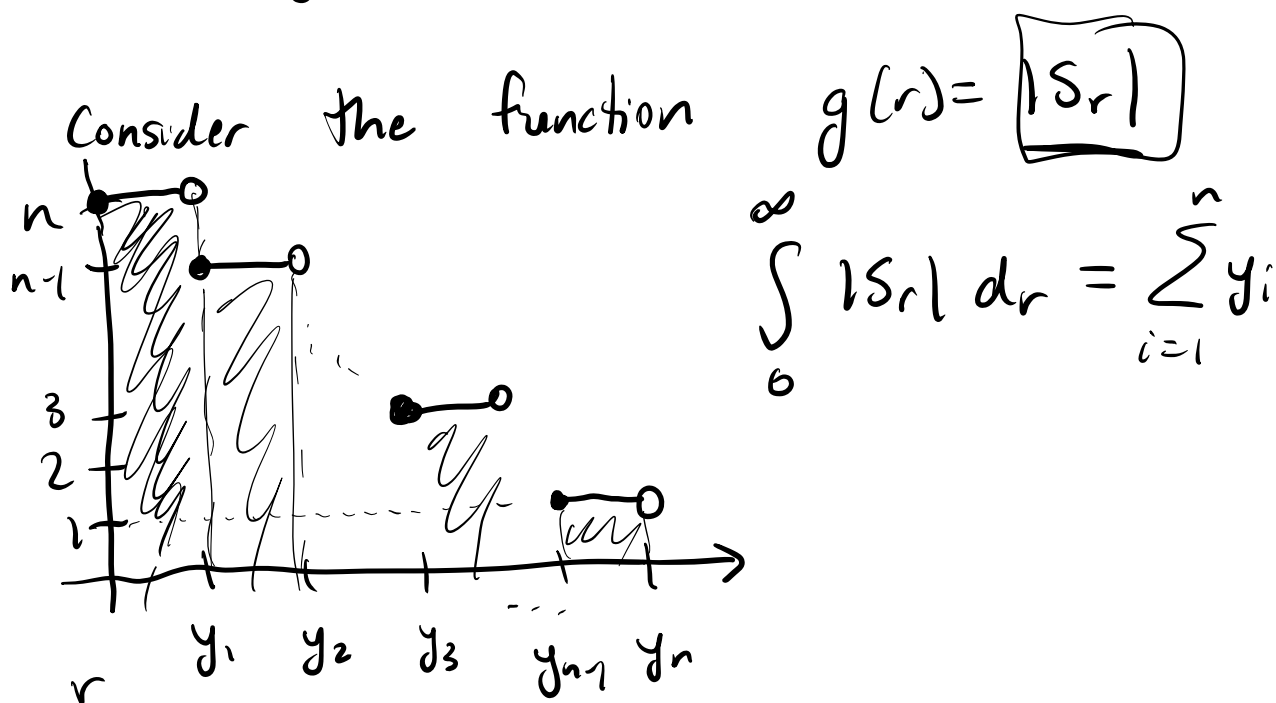
so $y_i \geq r, y_j \geq r$

so $x_{ij} = \min \{y_i, y_j\} \geq r$

$\Rightarrow ij \in E_r.$

Order nodes so that

$$y_1 \leq y_2 \leq \dots \leq y_n$$



$$\int_0^{\infty} |S_r| dr \approx n \cdot (y_1 - 0) + (n-1)(y_2 - y_1)$$

$$+ (n-2)(y_3 - y_2) - \dots - 2 \cdot (y_{n-1} - y_{n-2}) + 1 \cdot (y_n - y_{n-1})$$

$$= y_1 + y_2 + \dots + y_n = \sum_{i=1}^n y_i \leq 1$$

Similarly = $\int_0^\infty |E_r| dr = \sum_{i,j \in E} x_{ij} = \text{OPT}$

Claim = There is some $r \geq 0$
such that

$$\underline{f(S_r)} = \frac{|E_r|}{|S_r|} \geq \text{OPT}$$

If this were not true, then

$$\int_0^\infty |E(r)| dr < \int_0^\infty |S_r| \cdot \text{OPT} dr$$

$$\Rightarrow \sum_{i,j \in E} x_{ij} = \text{OPT} < \text{OPT} \cdot 1$$

$\exists$ some S_r $f(S_r) \geq \text{OPT}$.

